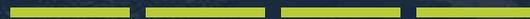




# Enabling Mars Exploration Through a Risk Informed Decision Framework



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# Background

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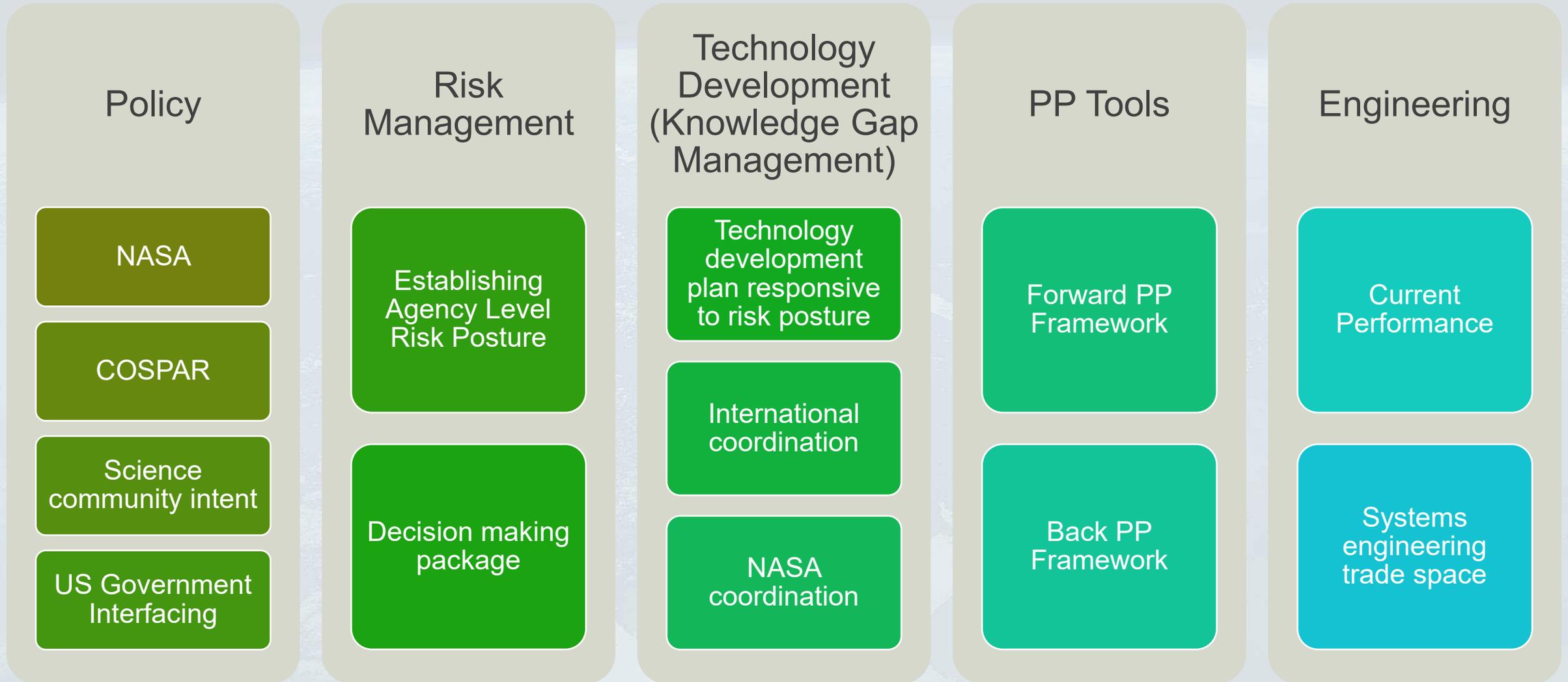
**Problem** – The current prescriptive planetary protection technical requirements not sufficient for large robotic (>1500m<sup>2</sup>), crewed, or in-situ resource utilization missions.

**Solution** – A performance-based framework is required for mission design and execution for both forward and backward PP.



Credits: NASA

# Multifaceted Moon-to-Mars PP Current Approach



# Mars Planetary Protection Requirement Landscape (1 of 2)

- COSPAR §4.6 “...Accordingly, planetary protection goals **should not be relaxed** to accommodate a human mission to Mars. Rather, they become even more directly relevant to such missions.”

## Robotic = Crew

### ► Forward PP Example





# PP Tools – Framework for Forward and Backward PP Risk

- Probabilistic tools need to be developed to enable Mars exploration.

	Current	Future Needs
Forward	<ul style="list-style-type: none"> <li>• Viking Pc analysis (reports)</li> <li>• Pc parameter assessment 1990s and special region</li> <li>• Europa Clipper model</li> </ul>	<ul style="list-style-type: none"> <li>• Modernize Mars Pc working model               <ul style="list-style-type: none"> <li>• Updated Mars mathematical framework</li> <li>• Updated biological &amp; environmental parameters</li> </ul> </li> </ul>
Backward	<ul style="list-style-type: none"> <li>• Robotic break the chain assurance framework</li> <li>• Sample Safety Assessment</li> </ul>	<ul style="list-style-type: none"> <li>• Crewed break the chain</li> <li>• Crew safety</li> <li>• Biosphere safety</li> </ul>

PP Tools

Forward PP Framework

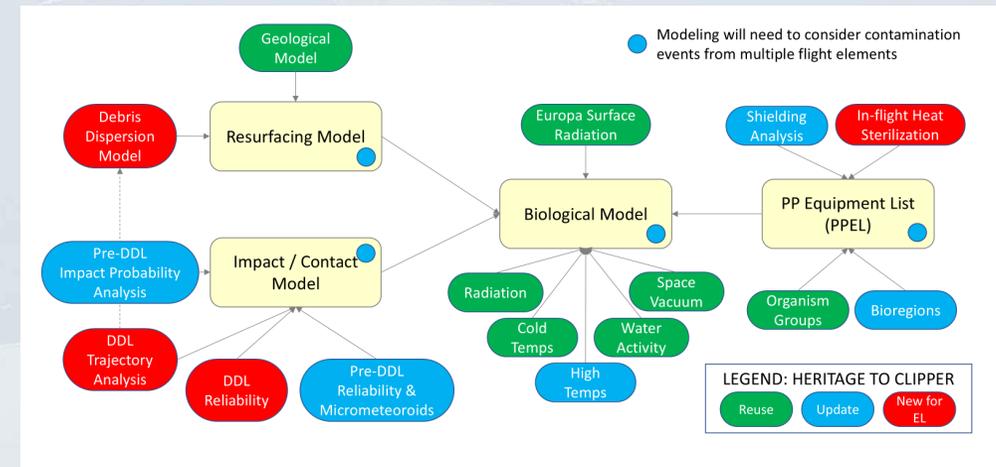
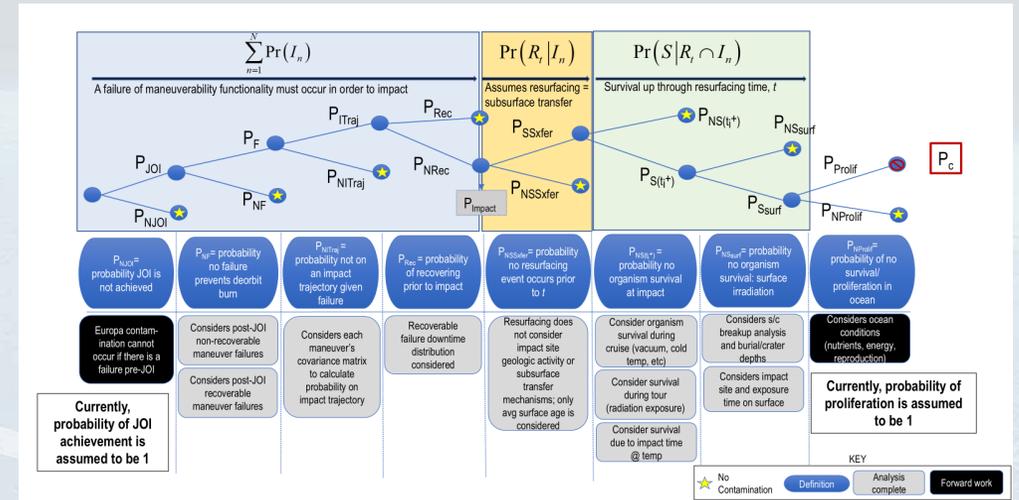
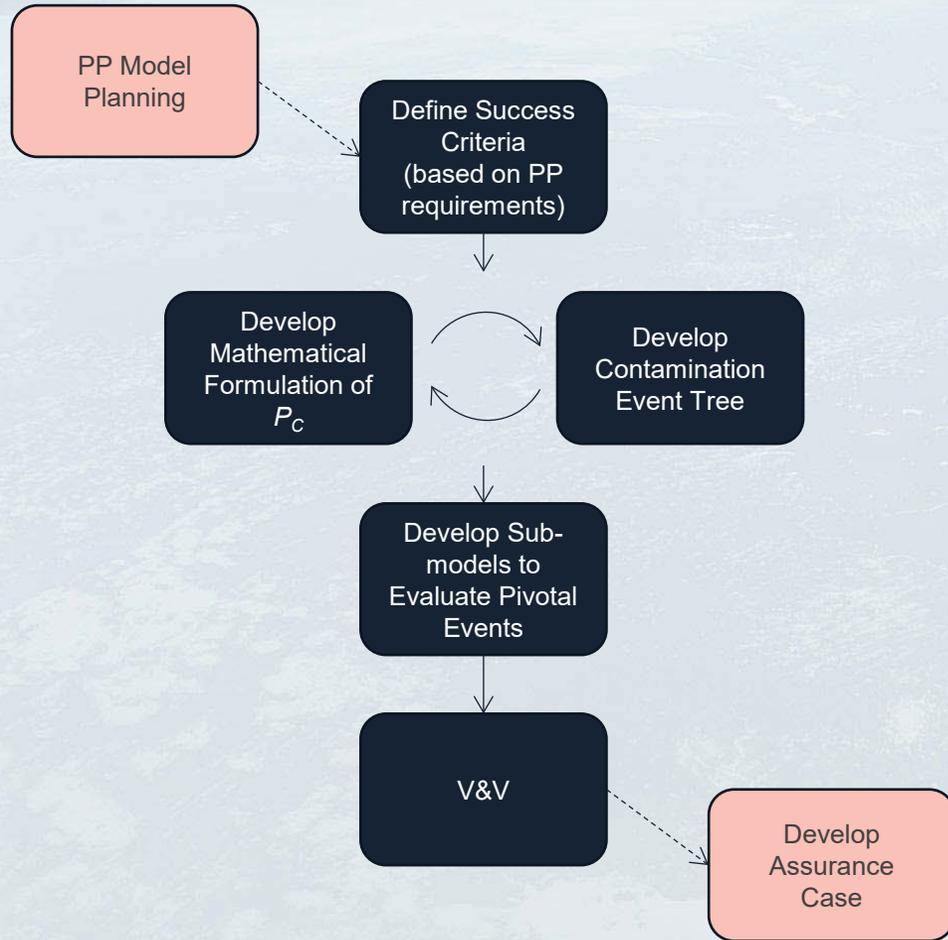
Back PP Framework

### Framework needs developed to:

- Harmonize and standardize the PP process.
- Assess the current state of Mars contamination through robotic exploration.
- Inform risk posture trade space.
- Inform technology developments and parameters by assessing modeling sensitivities/uncertainties.
- Support mission planning and execution.

# Modeling the Probability of Contamination for NASA Missions

► NASA Handbook SP-20240016475 - Appendix 4



Example of the network of submodels and analysis required for an icy world's probability of contamination model.

# Mars Forward Planetary Protection - Probability of Contamination – Background

- The Viking-based contamination equation is:

$$P_c = \sum N_0 P_s P_r P_g$$

– where:

- $P_c$  is the probability of contaminating Mars;
- $N_0$  is the number of organisms present before sterilization;
- $P_s$  is the probability that a randomly selected organism will survive sterilization;
- $P_r$  is the probability of release, and
- $P_g$  is the probability of growth

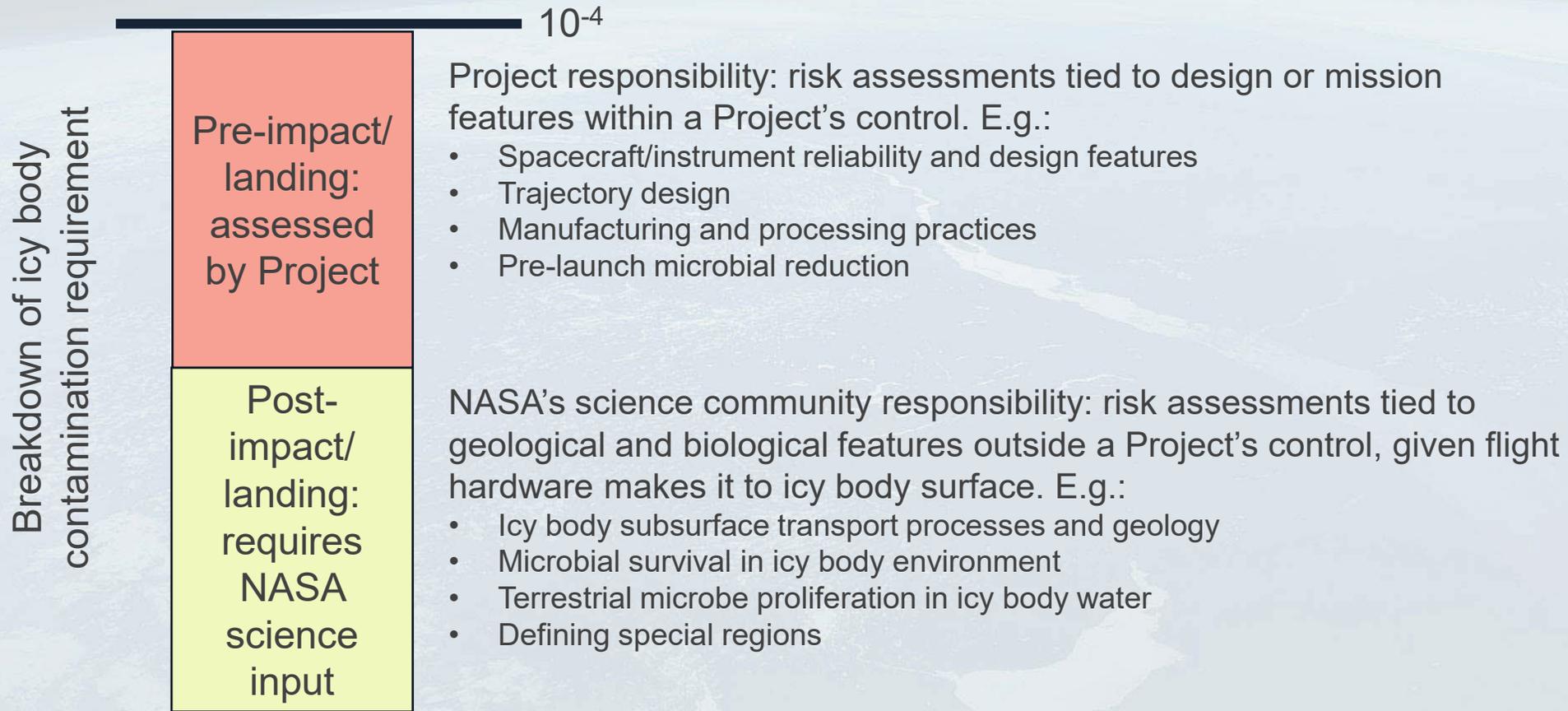
- Partial timeline of probability of contamination and probability of growth workshops, publications, and reports.

- 1964 – COSPAR establishes  $10^{-4}$
- 1970 – SSB report follow up with  $10^{-4}$  -  $10^{-6}$  values
- 1974 –  $P_c$  Viking report with Sagan Coleman approach - microbial characteristics, lethality of release / transport mechanisms and the martian environment
- 1978 –  $P_g$  report recommendation Mars regions (i.e., subsurface, polar ice caps)
- 1984 –  $P_c$  → Categories and simplification of  $P_c$  to spore NASA to COSPAR
- 1987 – SSB evaluation of  $P_c$
- 1991 – Mars Environmental Survey (MESUR) Mission Mini-Review
- 1992 – NCR report, NASA workshop
- 2002 – Special regions
- 2006 – Special Regions Science Analysis Working Group
- 2007 – NASEM recommends non-Mars missions convert to  $P_c$  ( $1e-4$ ) / mission
- 2014 – Special Regions Science Analysis Working Group 2
- 2021 – NASEM CoPP

Review publication planned for 2026!

# Icy World Probability of Contamination Breakdown – Project vs. Science

COSPAR: *probability of inadvertent ocean contamination*  $\leq 1 \times 10^{-4}$  ...







Questions?

